

Transversely Isotropic Hookean Material

orthotropic

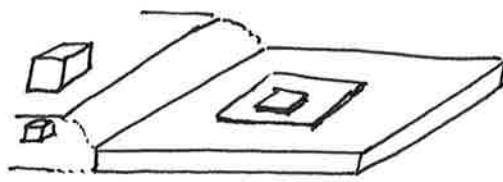
Consider a material with a "strong/stiff" direction and two weaker directions.



wood



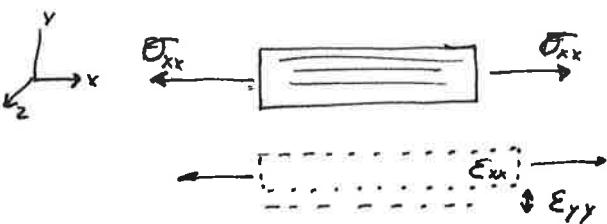
Unidirectional composite (e.g. CF tape)



Cold rolled metal (e.g. sheet metal)
flattened grain structure

Perform the same set of stress-strain tests

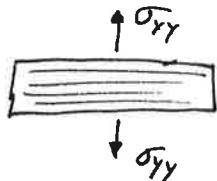
① Uniaxial along x direction



$$\sigma_{xx} = E_x \epsilon_{xx} \Rightarrow \epsilon_{xx} = \frac{\sigma_{xx}}{E_x}$$

$$G_{xy} = -\frac{\epsilon_{yy}}{\epsilon_{xx}}$$

② Uniaxial along y direction



$$E_y = \frac{\sigma_{yy}}{\epsilon_{yy}} \Rightarrow \epsilon_{yy} = \frac{\sigma_{yy}}{E_y}$$

$$G_{yz} = -\frac{\epsilon_{zz}}{\epsilon_{yy}}$$

③ Unidirectional along z direction

Same concept as ②

④ Shear in y-z plane



$$\epsilon_{yz} = \frac{\sigma_{yz}}{G_{yz}}$$

⑤ Shear in x-y direction (and x-z is similar)



$$\epsilon_{xy} = \frac{\sigma_{xy}}{G_{xy}}$$

Notice that this shear modulus is not the same as the G_{yz} modulus, since there are fibers in the x-direction!

Summation of strains (similar to previous) gives

$$\begin{pmatrix} \epsilon_{xx} \\ \epsilon_{yy} \\ \epsilon_{zz} \\ \epsilon_{yz} \\ \epsilon_{xz} \\ \epsilon_{xy} \end{pmatrix} = \begin{pmatrix} \frac{1}{E_x} & -\nu_{xy} & -\nu_{xy} \\ -\nu_{xy} & \frac{1}{E_y} & -\nu_{yz} \\ -\nu_{xy} & -\nu_{yz} & \frac{1}{E_z} \end{pmatrix} \begin{pmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{zz} \\ \sigma_{yz} \\ \sigma_{xz} \\ \sigma_{xy} \end{pmatrix}$$

$\frac{2(1+\nu_{yz})}{E_y}$

$\frac{1}{G_{xy}}$

$\frac{1}{G_{xy}}$

Material properties:

$$E_x, E_y, \nu_{xy}, \nu_{yz}, G_{xy}$$

Ex: Given Carbon Fiber unidirectional tape ($E_x \approx 25 \times 10^6 \text{ psi}$, $E_y \approx 2 \times 10^6 \text{ psi}$, $\nu = 0.3$
 $G_{xy} \approx 730 \text{ ksi}$)

Determine the strain given a load in the direction of the tape

$$\sigma_{xx} = 150 \text{ ksi} \quad \sigma_{yy} = 0 = \sigma_{zz}$$

$$\sigma_{yz} = 2 \text{ ksi} = \sigma_{xy} \quad \sigma_{xz} = 0$$

$$\epsilon_{xx} = \frac{\sigma_{xx}}{E_x} - \frac{\nu_{xy} \sigma_{xy}}{E_x} = \frac{150 \text{ ksi}}{25 \times 10^6 \text{ psi}} + \frac{1000 \text{ psi}}{730 \text{ ksi}} = 0.006$$

$$\epsilon_{yy} = -\frac{\nu_{xy}}{E_x} \sigma_{xx} = 0.3 \cdot 0.006 = 0.0018$$

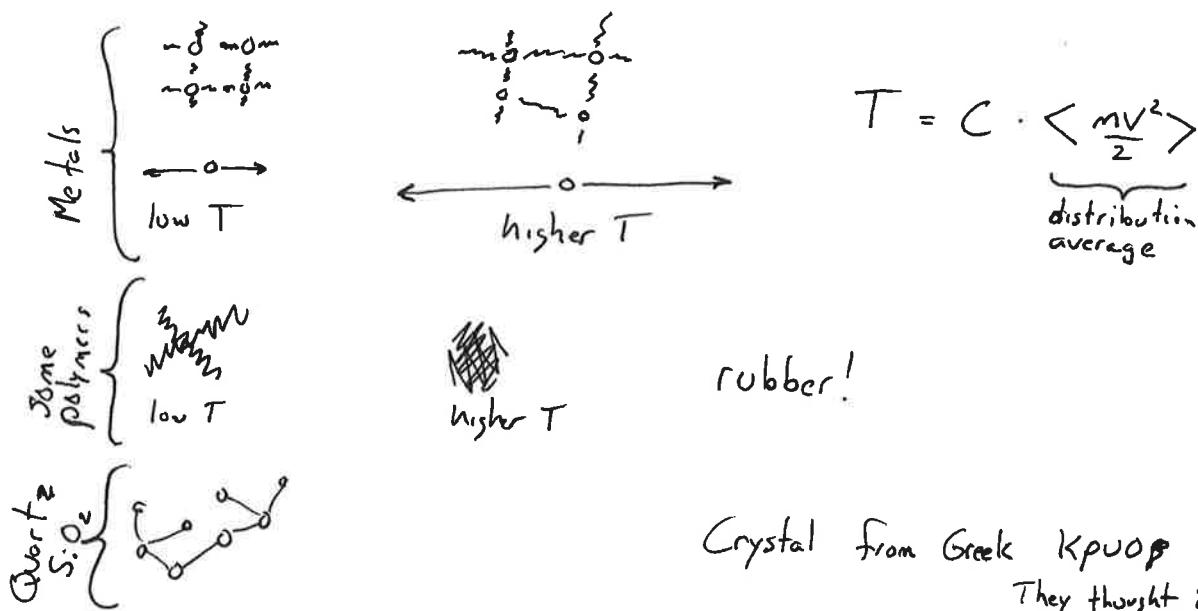
$$\epsilon_{zz} = 0.0018$$

$$\epsilon_{yz} = \frac{2(1+0.3)}{2 \times 10^6 \text{ psi}} \sigma_{xy}^2 \text{ ksi} = 0.0026$$

$$\epsilon_{xy} = \frac{\sigma_{xy}}{G_{xy}} = \frac{2 \text{ ksi}}{730 \text{ ksi}} = 0.00274$$

Thermoelastic Solids

Temperature is a measure of the microscopic vibrational kinetic energy distribution.



rubber!

Crystal from Greek Κρύος (ice cold)

They thought it was a
Special warm hard ice (H_2O).

"Quartz found near glaciers in mtns!"

Most materials expand with increasing temperature.

Some Polymers, Crystals, and even H_2O (at certain temps) contract with Temp.

The strain corresponding to a temperature change is (1st order expansion)

$$\epsilon = \alpha \Delta T$$

Ex: A $10^{in} \times 10^{in} \times 10^{in}$ block of 6061-T6 Al is heated from $0^{\circ}F$ to $200^{\circ}F$. Determine the change in volume.

$$V = 10 \cdot 10 \cdot 10 = 1000 \text{ in}^3$$

$$V_{\text{new}} = (10(1 + \alpha T)) = (10.026)^3$$

$$\Delta L_{\text{new}} = \alpha T \Delta T = \frac{13 \times 10^{-6}}{F} \frac{200 F}{=}$$

$$= 0.0026$$

$$= 1007.8 \text{ in}^3 \approx 0.8\%$$

Not a big deal, right?

Thermal can be a big deal

3D Isotropic Hookian Thermoelastic Material

Thermal Strain is: $\epsilon_{ii} = \alpha \Delta T$ $\epsilon_{ij} = 0$ when $i \neq j$

Strategy: Add strains together again.

$$\epsilon_{xx} = \frac{\sigma_{xx}}{E} - \frac{\nu}{E} \sigma_{yy} - \frac{\nu}{E} \sigma_{zz} + \alpha \Delta T$$

and ϵ_{yy} , ϵ_{zz} similarly...

Stress to strain

Add to previous 3D isotropic hookian ..

$$\begin{bmatrix} \epsilon_{xx} \\ \epsilon_{yy} \\ \epsilon_{zz} \\ \epsilon_{yz} \\ \epsilon_{xz} \\ \epsilon_{xy} \end{bmatrix} = \frac{1}{E} \begin{bmatrix} 1 & -\nu & -\nu \\ -\nu & 1 & -\nu \\ -\nu & -\nu & 1 \\ 0 & 0 & 2(1+\nu) \\ 0 & 2(1+\nu) & 0 \\ 0 & 0 & 2(1+\nu) \end{bmatrix} \begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{zz} \\ \sigma_{yz} \\ \sigma_{xz} \\ \sigma_{xy} \end{bmatrix} + \alpha \Delta T \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Invert $[C]$ to get $[D]$ after an algebra operation

$$(\epsilon) = [C](\sigma) + \alpha \Delta T(N) \Rightarrow [C](\sigma) = (\epsilon) - \alpha \Delta T(N)$$

$$(\sigma) = C^{-1}(\epsilon) - \alpha \Delta T [C]^{-1}(N)$$

But $[C]^{-1} = [D]$ and we have $[D]$ from before, so $\alpha \Delta T [C]^{-1} N = \alpha \Delta T [D] N$

$$\alpha \Delta T [C]^{-1}(N) = \alpha \Delta T \begin{bmatrix} 1 & -\nu & -\nu & \dots \\ -\nu & 1 & -\nu & \dots \\ -\nu & -\nu & 1 & \dots \\ \vdots & & & \ddots \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ \vdots \end{bmatrix} = \alpha \Delta T \begin{bmatrix} 1 & -\nu & -\nu & \dots \\ -\nu & 1 & -\nu & \dots \\ -\nu & -\nu & 1 & \dots \\ \vdots & & & \ddots \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ \vdots \end{bmatrix} = \cancel{\alpha \Delta T [D] N}$$

$$[C] = \begin{bmatrix} 1 & -v & -v \\ -v & 1 & -v \\ -v & -v & 1 \end{bmatrix} \quad \det(C) =$$

$$f_{11} = m_{33} \cdot m_{22} - m_{23}^2 = \underline{1-v^2} \quad f_{12} = \cancel{m_{33} \cdot v}^{v^2 + v} \quad f_{13} = v^2 + v = (1+v)v$$

$$f_{22} = 1-v^2 \quad f_{23} = v^2 + v = v(1+v)$$

$$f_{33} = 1-v^2$$

$$\begin{aligned} \det(C) &= 1 \cdot (1-v^2) + -v(v+1) + (-v)v(1+v) \\ &= (1-v^2) - 2v^2(v+1) = 1-v^2 - 2v^3 - 2v^2 = (2v-1)(-1)(v+1)^2 \end{aligned}$$

~~Terms~~

$$\frac{1-v^2}{(1-2v)(v+1)^2} = \frac{(1-v)(1+v)}{(1-2v)(1+v)(1+v)} = \frac{1-v}{(1-2v)(1+v)}$$

$$\frac{v^2+v}{(1-2v)(v+1)^2} = \frac{v(1+v)}{(1-2v)(v+1)(v+1)} = \frac{v}{(1-2v)(v+1)}$$

$$[D] = \frac{E}{(1-2v)(1+v)} \begin{bmatrix} 1-v & v & v \\ v & 1-v & v \\ v & v & 1-v \end{bmatrix}$$

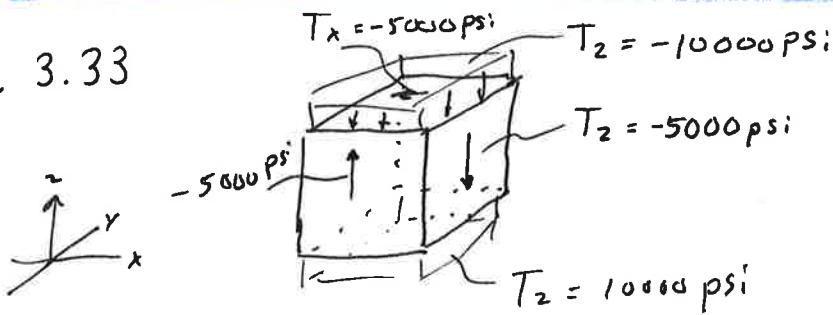
$$\alpha \Delta T [C](N) = \alpha \Delta T [D]_N = \frac{\alpha \Delta T E}{(1-2v)(1+v)} \begin{pmatrix} 1-v+v+v \\ 1-v+v+v \\ 1-v+v+v \end{pmatrix} \cancel{\begin{pmatrix} 1+v \\ 1+v \\ 1+v \end{pmatrix}}$$

$$= \frac{\alpha \Delta T E}{(1-2v)} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

Strain to Stress

$$\begin{pmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{zz} \\ \sigma_{xy} \\ \sigma_{xz} \\ \sigma_{xy} \end{pmatrix} = \frac{E}{(1+\nu)(1-2\nu)} \begin{pmatrix} 1-\nu & \nu & \nu \\ \nu & 1-\nu & \nu \\ \nu & \nu & 1-\nu \end{pmatrix} \begin{pmatrix} \epsilon_{xx} \\ \epsilon_{yy} \\ \epsilon_{zz} \\ \epsilon_{yz} \\ \epsilon_{xz} \\ \epsilon_{xy} \end{pmatrix} - \frac{\alpha \Delta T E}{1-2\nu} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Ex. 3.33



$$\alpha = +13 \times 10^{-6}/F$$

$$\nu = 0.30$$

$$\Delta T = 100^F$$

$$k = 10 \times 10^6 \text{ psi}$$

Stress

$$\sigma_{zz} = 10 \text{ ksi}; \quad \sigma_{xx} = 0 \quad \sigma_{yy} = 0 \quad \sigma_{xy} = 0 \quad \sigma_{xz} = -5 \text{ ksi}$$

Bulk Mod'

$$k = \frac{E}{3(1-2\nu)} \Rightarrow E = k \cdot 3 \cdot (1-2\nu) = 10 \times 10^6 \text{ psi} \cdot 3 \cdot (1-2 \cdot 0.3) = 12 \times 10^6 \text{ psi}$$

Strains

$$\epsilon_{xx} = \frac{\sigma_{xx} - \nu \sigma_{yy} - \nu \sigma_{zz}}{E} = \frac{-0.3 \cdot 10 \text{ ksi}}{12 \times 10^6 \text{ psi}} = \boxed{0.00025}$$

$$\epsilon_{yy} = 0.00025$$

$$\epsilon_{zz} = \frac{\sigma_{zz}}{E} = \boxed{0.00083}$$

$$\epsilon_{xz} = \frac{2(1+\nu)\sigma_{xz}}{E} = \frac{2(1.3)(-5 \text{ ksi})}{12 \times 10^6 \text{ psi}} = \boxed{0.0011}$$

principal stresses

$$\text{eigval } (\sigma) = \text{eigval} \begin{pmatrix} 0 & 0 & -5 \\ 0 & 0 & 0 \\ -5 & 0 & 10 \end{pmatrix} = \boxed{12.0, -2.0, 0.0 \text{ ksi}}$$

$$\sigma_{max} = \frac{12 - (-2)}{2} = \frac{14}{2} = \boxed{7 \text{ ksi}}$$

Composites

Nomenclature and Terminology is often derived from textile industry.

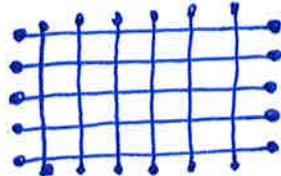
Single fiber → filament (1)

Multiple filaments → strand (100)

Multiple strands → tow (3000)

twisted strands → yarn
Not as common in auto

Woven tow
"Cloth"



weft "across the cloth"
warp "along the cloth"

Chopped Strand Mat
"CSM"



Usually glass fibers chopped and then randomly oriented in a "mat" held together with a binder "temp glue"

Tapes



Can be uni or woven

Pre-preg

the matrix (in an uncured state) is applied to the material

Usually stored in a freezer, limited shelf life, Wonderful to use!
precise fiber to matrix ratio

Alternative ways to determine eigenvalues of a 3×3 $[\sigma]$

TI-84 youtu.be/n9-39MwNKGc

solve $\det(x(\text{Identity}(2)) - M)$
good guesses

Numerical Solver

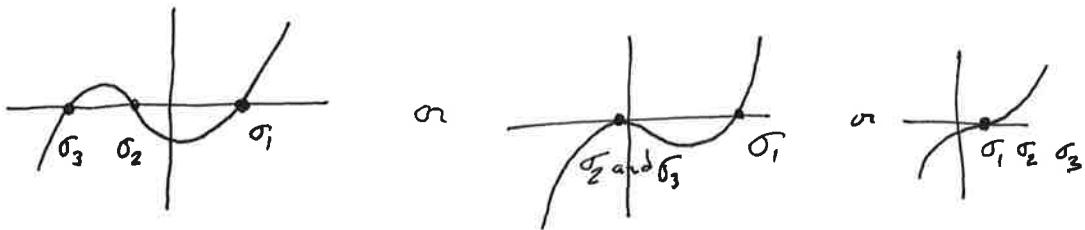
$$I_1 = \sigma_{xx} + \sigma_{yy} + \sigma_{zz}$$

$$I_2 = \begin{vmatrix} \sigma_{xx} & \sigma_{xy} \\ \sigma_{xy} & \sigma_{yy} \end{vmatrix} + \begin{vmatrix} \sigma_{yy} & \sigma_{yz} \\ \sigma_{yz} & \sigma_{zz} \end{vmatrix} + \begin{vmatrix} \sigma_{zz} & \sigma_{zx} \\ \sigma_{zx} & \sigma_{xx} \end{vmatrix}$$

$$I_3 = \det(\sigma) = \begin{vmatrix} \sigma_{xx} & \sigma_{xy} & \sigma_{xz} \\ \sigma_{xy} & \sigma_{yy} & \sigma_{yz} \\ \sigma_{xz} & \sigma_{yz} & \sigma_{zz} \end{vmatrix}$$

$$-\sigma_p^3 + I_1\sigma_p^2 - I_2\sigma_p + I_3 = 0$$

plot ↑ as $y(x) = -x^3 + I_1x^2 - I_2x + I_3$



Online

www.bluebit.gr/matrix-calculator

Matlab