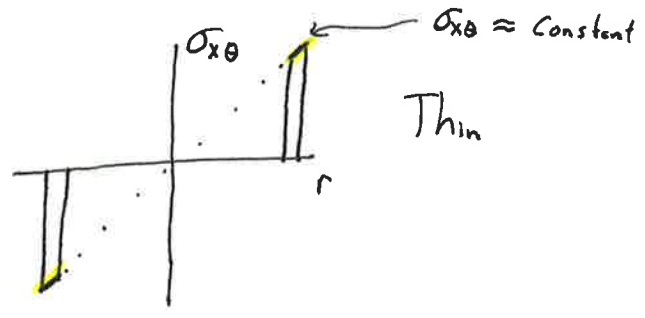
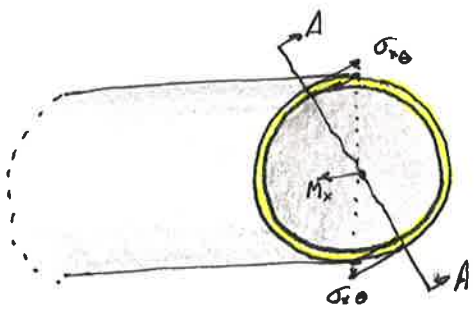
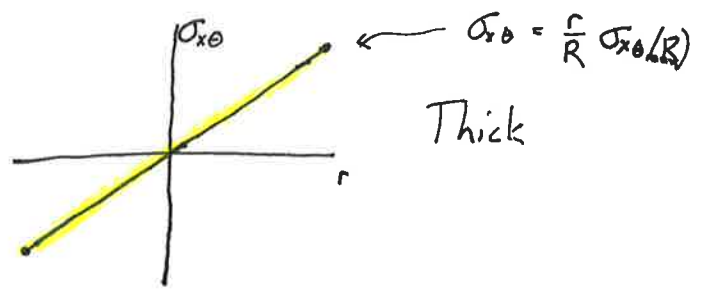
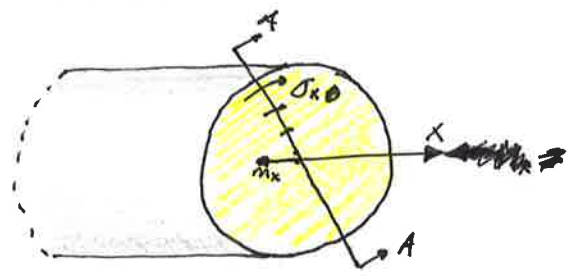


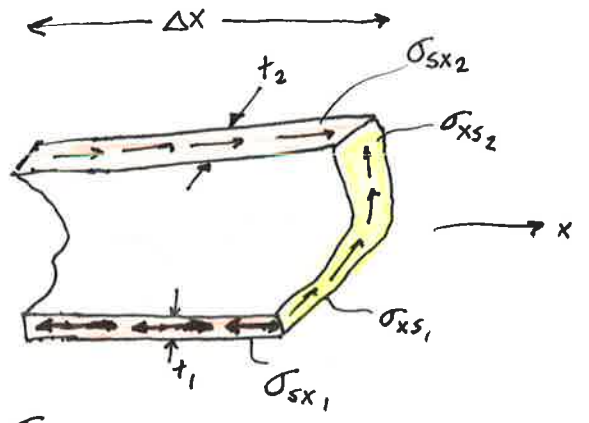
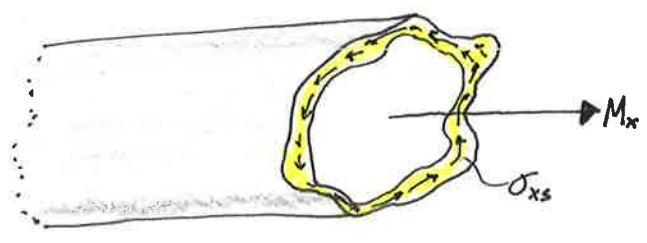
# Thin Walled Closed Sections in Torsion

Thin wall  $\equiv$  stress is relatively constant across the wall thickness.

Thick wall  $\equiv$  stress is NOT constant across the wall thickness



## Generic Thin Walled Closed Section



For no rotation  $\sigma_{xs_1} = \sigma_{sx_1}$  and  $\sigma_{xs_2} = \sigma_{sx_2} \Rightarrow \sum M = 0$  static

Sum forces in x-direction

$$\sum F_x = 0 = -\sigma_{sx_1} (\Delta x) (t_1) + \sigma_{sx_2} (\Delta x) (t_2)$$

Thus  $\sigma_{xs_1} t_1 = \sigma_{xs_2} t_2 = \text{constant for a given } M_x !!$

We call this constant

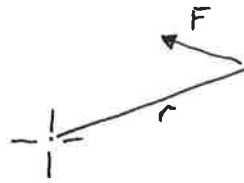
$$\text{Shear flow} = q \equiv \sigma_{xs} t$$

Units  $[\text{psi}][\text{in}] = \left[ \frac{\text{lb} \cdot \text{f}}{\text{in}} \right]$

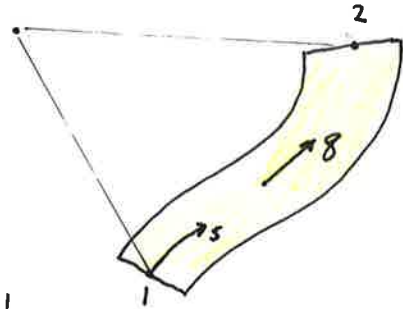
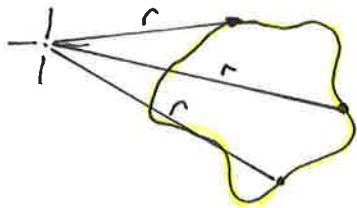
# Torque about a point

$$M = r \times F$$

$$dM = r \times dF$$



Pick a section of our thin walled closed section with an arbitrary point for M



$$F = q ds$$

$q$  is always in the  $s$  direction since thin walled

$$T_{12} = M_{12} = \int_1^2 r \times q ds$$

But  $r = r(s)$  ~~and  $r$  is a function of  $s$~~

$$M = \int_1^2 r(s) \times q ds \quad q \text{ is a constant}$$

$$= q \int_1^2 r(s) \times ds$$

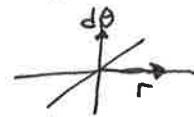
This looks complicated but remember that  $ds = d\theta \times r$



$$M = q \int_1^2 r(s) \times (d\theta \times r)$$

and the vector triple product is  $a \times (b \times c) = b(a \cdot c) - c(a \cdot b)$

$$r \times (d\theta \times r) = \underbrace{d\theta(r \cdot r)}_{r^2} - r(r \cdot d\theta)$$



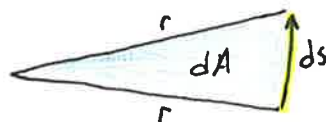
$$r \cdot d\theta = 0 !$$

$$= d\theta r^2 - 0$$

and  $r d\theta = ds$

$$M = q \int_1^2 r ds$$

$$= q \int_1^2 2dA$$



The area of this differential piece is  $\frac{1}{2} r ds = dA$

$$\text{or } 2dA = r ds$$

$$T_{12} = M_{12} = 2q \int_1^2 dA$$

all around section  
See Fig. 4.20

$$T = 2q \bar{A}$$

$$\Rightarrow q = \frac{M_x}{2A}$$

This is an important result. Shear flow depends on the applied moment and the cross section's area.

Ex:

A thin walled box section is subjected to 100 lbf-in. The interior area is 10 in<sup>2</sup>. What is the shear flow?

$$q = \frac{M_x}{2A} = \frac{100 \text{ lbf-in}}{2 \cdot 10 \text{ in}^2} = \boxed{5 \frac{\text{lbf}}{\text{in}} = q}$$

If the wall thickness is 0.010 inches at a point A, what is  $\sigma_{xs}$  at A?

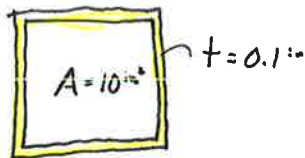
$$\sigma_{xs} = \frac{q}{t} = \frac{5 \frac{\text{lbf}}{\text{in}}}{0.01 \text{ in}} = \boxed{500 \text{ psi} = \sigma_{xs}}$$

Have we specified the exact geometry yet?

No

Ex: 4.20

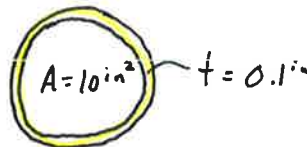
<sup>3</sup>  
~~Two~~ cross sections are given. Determine the one with the lowest  $\sigma_{xs}$ .



①

$$q = \frac{M_x}{2A} = \frac{M_x}{20 \text{ in}^2}$$

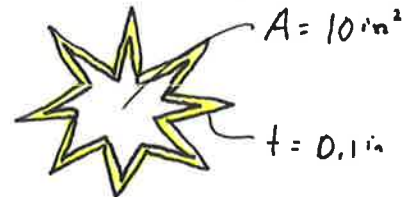
$$\sigma_{xs} = \frac{q}{t} = \frac{M_x}{2 \text{ in}^3}$$



②

$$q = \frac{M}{2A} = \frac{M_x}{20 \text{ in}^2}$$

$$\sigma_{xs} = \frac{q}{t} = \frac{M_x}{2 \text{ in}^3}$$



$$q = \frac{M_x}{20 \text{ in}^2} \quad \underline{\text{Same}}$$

$$\sigma_{xs} = \frac{M_x}{2 \text{ in}^3} \quad \underline{\text{Same}}$$

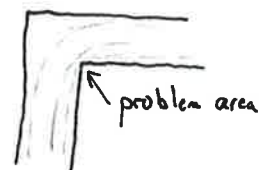
Theory says these are absolutely exactly the same.

Reality:

Stress concentrations

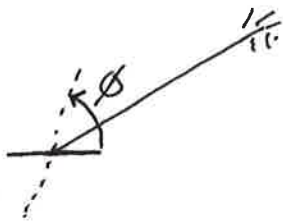


VS



think fluid flow

# Torsional Deformation



Define a twist per unit length as

$$\Theta = \frac{d\phi}{dx} \Rightarrow d\phi = \Theta dx$$

$$\int d\phi = \int \Theta dx$$

$$\phi = \int \Theta dx$$

Remember back to the kinematics section of the class

$$\epsilon_{ij} = \frac{\partial u_j}{\partial i} + \frac{\partial u_i}{\partial j} \Rightarrow \epsilon_{xs} = \frac{\partial u}{\partial s} + \frac{\partial \eta}{\partial x}$$



$\eta = r\phi =$  length of displacement due to rotation

And  $\sigma_{xs} = G \epsilon_{xs} \Rightarrow \epsilon_{xs} = \frac{\sigma_{xs}}{G} = \frac{\partial u}{\partial s} + \frac{\partial \eta}{\partial x}$

$$= \frac{\partial u}{\partial s} + \frac{\partial (r\phi)}{\partial x}$$

$$= \frac{\partial u}{\partial s} + r \frac{\partial \phi}{\partial x} = \frac{\partial u}{\partial s} + r\Theta$$

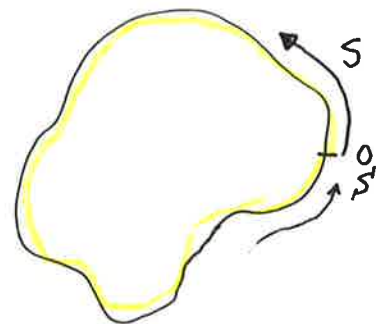
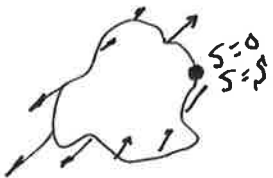
Also,  $\sigma_{xs} = \frac{\tau}{t}$  so,  $\frac{\sigma_{xs}}{G} = \frac{\tau}{Gt} = \frac{\partial u}{\partial s} + r\Theta$

Solve for  $\frac{du}{ds}$

$$\frac{du}{ds} = \frac{\tau}{Gt} - r\Theta \quad \text{multiply by } ds \quad du = \frac{\tau}{Gt} ds - r\Theta ds$$

Integrate around  $S$  (i.e. the outside edge)

$$\oint_S du = \oint_S \frac{\tau}{Gt} ds - \oint_S r\Theta ds$$



$$\int_s du = U(s=g) - U(s=0)$$



Same point!

$$\oint du = \underline{\underline{0}}$$

Thus

$$\oint_{s'} r \theta ds = \int_{s'} \frac{q}{Gt} ds$$

Remember this?  $\theta \neq \theta(s)$  and is a constant in here

$$\theta \int r ds = \theta \cdot 2A$$

Thus,

$$\theta = \frac{1}{2A} \int \frac{q}{Gt} ds$$

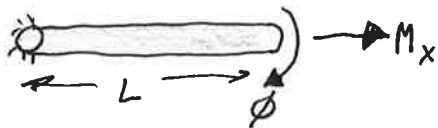
### Torsional Rigidity



Spring constant

$$F = +Kx \quad \Rightarrow \quad K = \frac{+F}{x}$$

Similarly



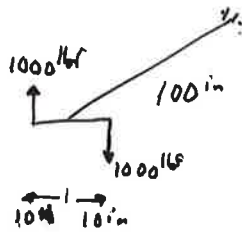
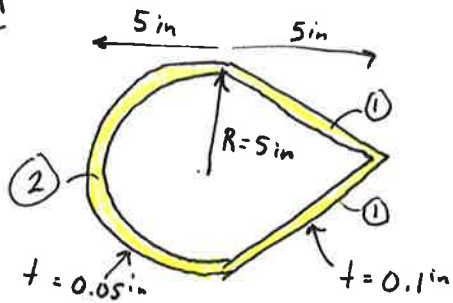
$$\theta = \frac{d(\text{rotation})}{d(\text{Length})} = \frac{\phi}{L}$$

Torsional Rigidity =

$$TR = \frac{M_x}{\theta}$$

Think of a rotational spring constant

Ex: 4.19



part	G
1	$5 \times 10^6$ psi
2	$12 \times 10^6$ psi

① Loading

$$M_x = r \times F = -10 \text{ in} \cdot 1000 \text{ lbf} + 10 \text{ in} \cdot (-1000 \text{ lbf})$$

$$M_x = -20000 \text{ lbf in}$$

② Geometry

$$\begin{aligned} \text{Area} &= \text{Circle} + \text{Triangle} = \frac{\pi R^2}{2} + \frac{h \cdot w}{2} = \frac{\pi 5^2}{2} + \frac{10 \cdot 5}{2} \\ &= 64.3 \text{ in}^2 \end{aligned}$$

③ Shear flow

$$q = \frac{M_x}{2A} = \frac{-20000 \text{ lbf in}}{2 \cdot 64.3 \text{ in}^2} = -155.6 \frac{\text{lbf}}{\text{in}}$$

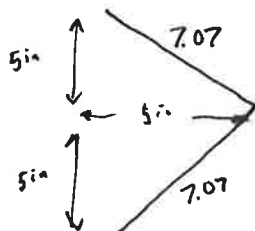
④ Shear Stress

$$\sigma_{\text{shear part 1}} = \frac{q}{t} = \frac{-155.6 \text{ lbf/in}}{0.1 \text{ in}} = \boxed{-1.56 \text{ ksi}}$$

$$\sigma_{\text{shear part 2}} = \frac{q}{t} = \frac{-155.6 \text{ lbf/in}}{0.05 \text{ in}} = \boxed{-3.12 \text{ ksi}}$$

⑤ Twist

$$\begin{aligned} \theta &= \frac{1}{2A} \int \frac{q}{Gt} ds = \frac{1}{2A} \int_1 \frac{q_1}{G_1 t_1} ds + \frac{1}{2A} \int_2 \frac{q_2}{G_2 t_2} ds \quad \text{but } q_1 = q_2 = q \\ &= \frac{q}{2A} \left[ \frac{1}{5 \times 10^6 \text{ psi} \cdot 0.1 \text{ in}} \cdot 14.14 \text{ in} + \frac{1}{12 \times 10^6 \text{ psi} \cdot 0.05 \text{ in}} \cdot 15.7 \right] \end{aligned}$$



$$C = \frac{\pi D}{2} = 15.7$$

$$\theta = \frac{-155.6 \text{ lbf} \cdot \text{in}}{\text{in} \cdot 2 \cdot 64.3 \text{ in}^2} \left( \frac{14.14 \text{ in}}{5 \times 10^6 \text{ psi} \cdot 0.1 \text{ in}} + \frac{15.7 \text{ in}}{12 \times 10^6 \text{ psi} \cdot 0.05 \text{ in}} \right)$$

$$= -0.000066 \frac{\text{rad}}{\text{in}}$$

$$\text{Total twist} = \phi = \int \theta dx = \theta \cdot L = \boxed{-0.0066 \text{ rad} = \phi}$$

⑥ Torsional rigidity

$$TR = \frac{M_x}{\theta} = \frac{-20000 \text{ lbf} \cdot \text{in}}{-0.000066 \text{ rad/in}} = \boxed{3.0 \times 10^8 \frac{\text{lbf} \cdot \text{in}^2}{\text{rad}}}$$

Compare (Roughly) to broken section



$$J_1 \approx \frac{5t^3}{3} = \frac{14.14 \text{ in} \cdot 0.1^3 \text{ in}^3}{3}$$

$$= 0.0047 \text{ in}^4$$

$$J_2 = \frac{15.7^3 \cdot 0.05^3 \text{ in}^3}{3}$$

$$= 0.0065 \text{ in}^4$$

$$TR = GJ \approx \sum GJ = (5 \times 10^6 \text{ psi})(0.0047 \text{ in}^4) + (12 \times 10^6 \text{ psi})(0.0065 \text{ in}^4)$$

$$= 31416.7 \frac{\text{lbf} \cdot \text{in}^2}{\text{rad}}$$

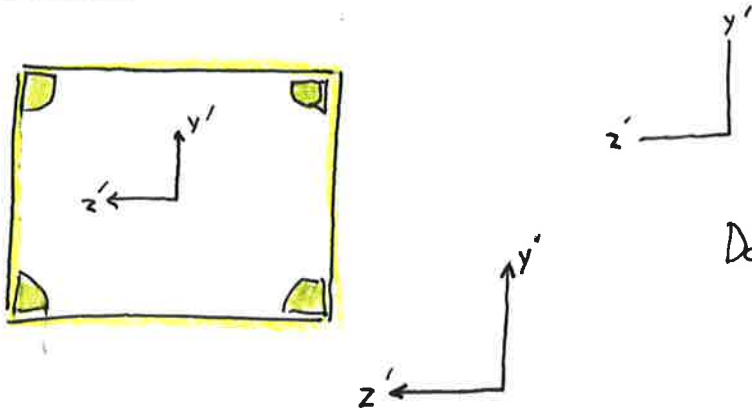
$$\theta = \frac{M_x}{TR} = \frac{-20000 \text{ lbf} \cdot \text{in}}{31416.7 \text{ lbf} \cdot \text{in}^2/\text{rad}} = -0.636 \frac{\text{rad}}{\text{in}}$$

$$\phi \equiv \text{total twist} = L \cdot \theta = -63 \text{ rad} \quad !!$$

= 10 twists

TR is .01% of closed section.

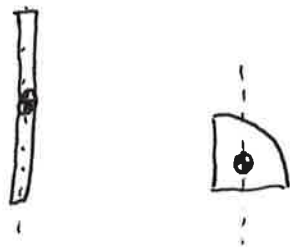
# Computing Modulus Weighted $I_{yz}$ $I_{yy}$ $I_{zz}$



Does the reference frame matter?

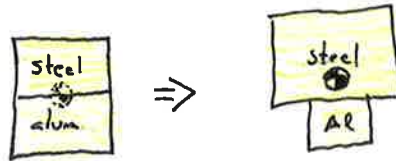
No

① Calculate  $I_{xy}$  of each part about its centroid



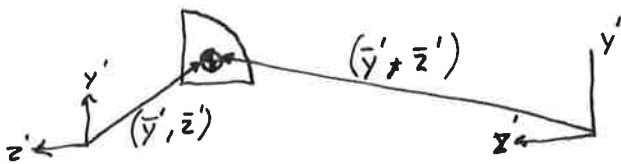
② Modulus weighted Area

$$A^* = \sum \frac{E}{E_i} A$$



As if the geometry were scaled by E

③ distance to centroid from reference frame  $y' z'$



④ Total MoI about cross section's modulus weighted centroid

$$I_{yy}^* = \underbrace{\frac{E}{E_i} \left( \underbrace{I_{xy}}_{\text{modulus about } y'z' \text{ frame}} + \underbrace{\bar{z}_i^2 A_i}_{\text{modulus weighted centroid}} \right)}_{\text{weighted modulus}} - \underbrace{\bar{z}^{*2} A^*}_{\text{shift to modulus weighted centroid}}$$

MW Centroid  $I_{yy}^*$

$\bar{z}_i$  is the distance from the  $y'z'$  frame to the part's centroid

$\bar{z}^*$  is the distance from the  $y'z'$  frame to the MW centroid

