

# Biharmonic Equation

$$\nabla^4 U = 0 \quad (\text{aka } \nabla^2 \nabla^2 U = 0)$$

- By inspection, every solution of  $\nabla^2 U = 0$  also is a solution of  $\nabla^4 U = 0$

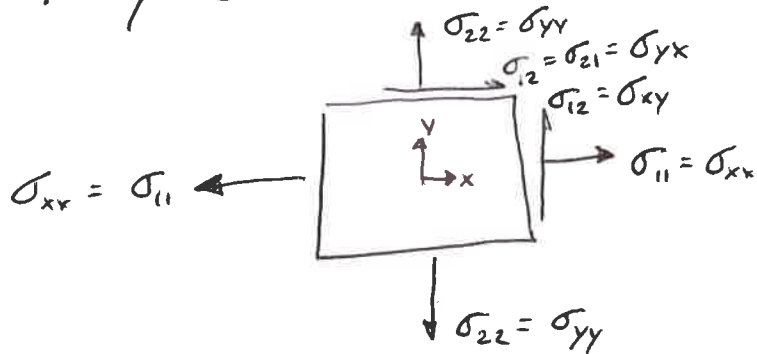
But not every solution of the biharmonic equation satisfies Laplace's equation.

- Cartesian coordinates

$$\nabla^4 U = \frac{\partial^4 U}{\partial x^4} + 2 \frac{\partial^4 U}{\partial x^2 \partial y^2} + \frac{\partial^4 U}{\partial y^4} = 0$$

Warning: Not every conformal map for  $\nabla^2 U = 0$  works for  $\nabla^4 U = 0$

- Airy Stress function  $\Phi$ ,  $\nabla^4 \Phi = 0$



$$\sigma = \begin{bmatrix} \sigma_{11} & \sigma_{21} \\ \sigma_{12} & \sigma_{22} \end{bmatrix} = \begin{bmatrix} \sigma_{xx} & \sigma_{yx} \\ \sigma_{xy} & \sigma_{yy} \end{bmatrix}$$

$$\sigma_{xx} = \sigma_{11} = \Phi_{yy}$$

$$\sigma_{yy} = \sigma_{22} = \Phi_{xx}$$

$$\sigma_{xy} = \sigma_{12} = \sigma_{21} = -\Phi_{xy}$$

Compatibility?  $\nabla^2 (\sigma_{11} + \sigma_{22}) = 0 \quad \checkmark$

$$\nabla^2 (\Phi_{yy} + \Phi_{xx}) = 0$$

$$\Phi_{yyxx} + \Phi_{yyxy} + \Phi_{xxxy} + \Phi_{xxyy} = 0$$

definition of  $\Delta^2 \Phi = 0 \quad \checkmark$

- Any polynomial of order less than 4 is biharmonic. (trivial soln!)

$$\begin{array}{ccccccc}
 & & & & X & & Y \\
 & & & & x^2 & & xy & & y^2 \\
 & & & & x^3 & & x^2y & & xy^2 & & y^3 \\
 & & & & x^3y & & x^2y^2 & & xy^3 & & y^4
 \end{array}$$

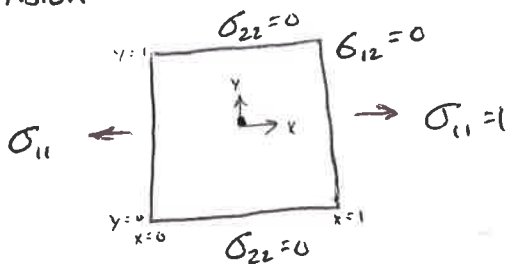
$$\phi = A + Bx + Cy + Dx^2 + Exy + Fy^2 + Gx^3 + Hx^2y + Ixy^2 + Jy^3 + Kx^3y + Lx^2y^2 + Mxy^3 + Nx^3y^2 + Px^2y^3 + Qxy^4$$

$$\sigma_{yy} = \phi_{yy} = 2F + 2Ix + 6Jy + 2Lx^2 + 6Mxy + 6Nx^3y + 2Px^3 + 6Qxy^3$$

$$\sigma_{xx} = \phi_{xx} = 2D + 6Gx + 2Hy + 6Kxy + 2Ly^2 + 6Nxy^3 + 6Px^2y^2 + 2Qy^4$$

$$\sigma_{xy} = \phi_{xy} = E + 2Hx + 2Iy + 3Kx^2y + 4Lxy^2 + 3My^3 + 9Nx^2y^2 + 6x^2y^3 + 6xy^4$$

- Tension



$$\begin{aligned}
 \sigma_{xx} &= \begin{cases} 1 & \text{on left + right faces} \\ 0 & \text{otherwise} \end{cases} \\
 \sigma_{yy} &= 0 \quad \text{on all surfaces B.C.s} \\
 \sigma_{xy} &= 0 \quad \text{on all " " " "}
 \end{aligned}$$

$$\begin{aligned}
 \sigma_{xx}(x=0, y=0 \dots 1) &= 1 = 2F + 2I \cdot 0 + 6Jy \quad \Rightarrow \quad 1 = 2F + 0 \\
 \sigma_{xx}(x=1, y=0 \dots 1) &= 1 = 2F + 2I \cdot 1 + 6Jy \quad \Rightarrow \quad 1 = 2F + 2I
 \end{aligned}$$

$$\begin{aligned}
 \sigma_{yy}(y=0, x=0 \dots 1) &= 0 = 2D + 6Gx + 2H \cdot 0 \\
 \sigma_{yy}(y=1, x=0 \dots 1) &= 0 = 2D + 6Gx + 2H
 \end{aligned}$$

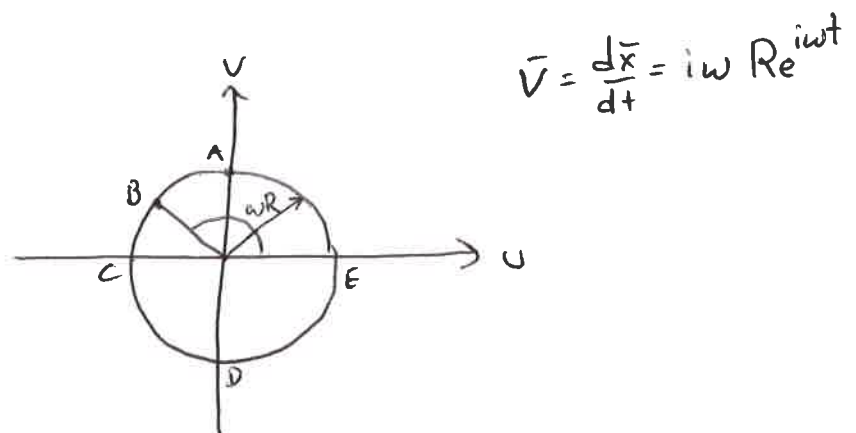
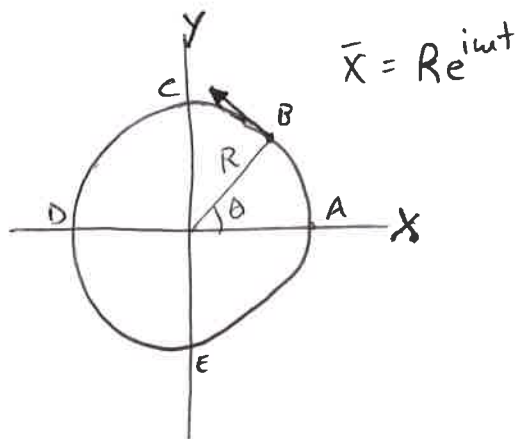
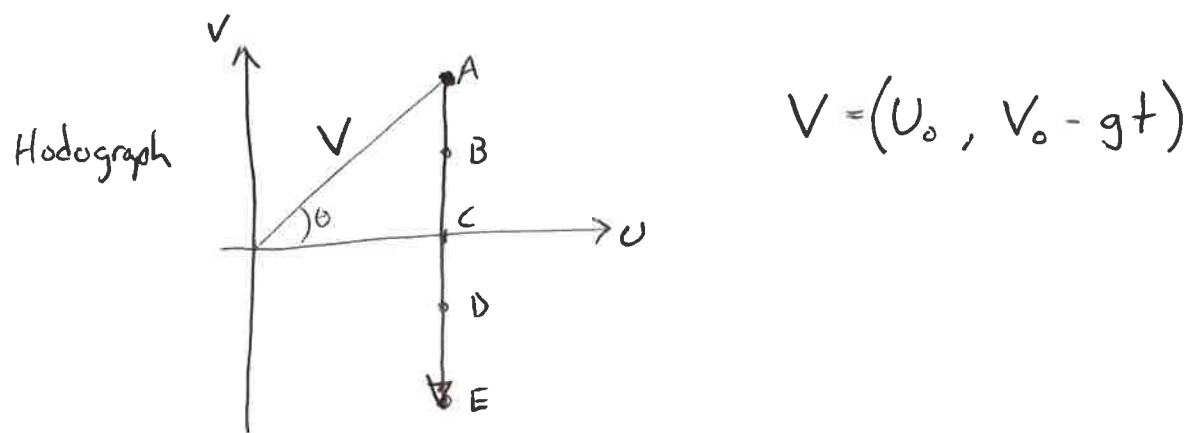
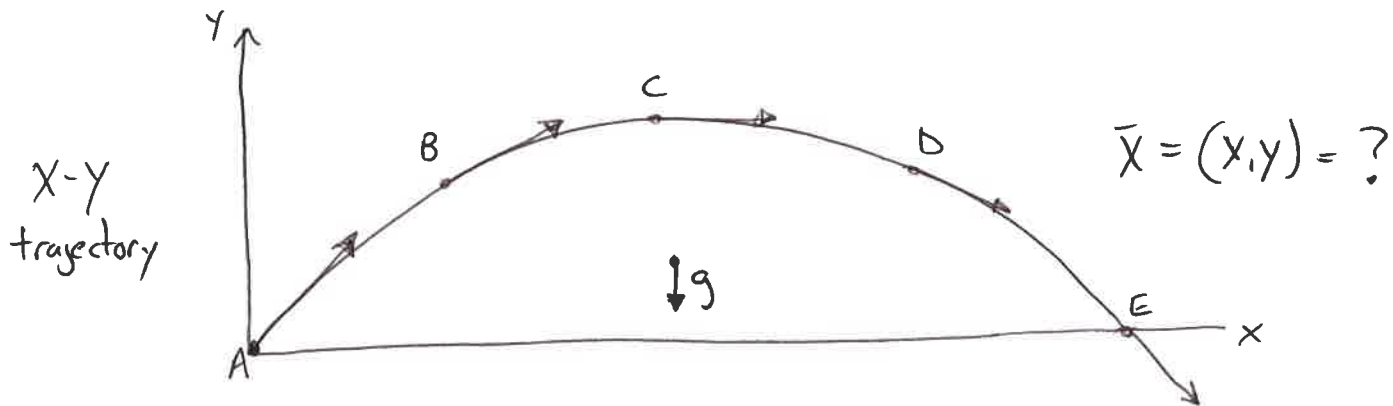
$$D = 0, H = 0$$

$$\sigma_{xy}(\text{all}) = E + 2Hx + 2Iy = 0 \quad \Rightarrow \quad E = 0$$

$$\boxed{\phi = \frac{1}{2}y^2}$$

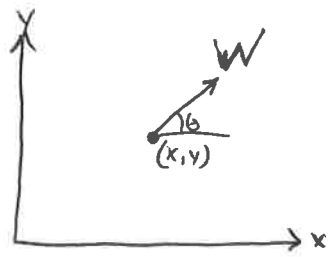
$$\sigma_{xx}(x,y) = \phi_{yy} = 1 \quad \checkmark$$

# Hodograph



Hodograph  
 "write" in Greek  
 Greek "path"

Ref: Analytical Fluid Dynamics  
 George Emanuel



$$u = W \cos \theta$$

$$v = W \sin \theta$$

$$u = \phi_x, \quad v = \phi_y, \quad u = \frac{p_0}{\rho} \psi_y, \quad v = -\frac{p_0}{\rho} \psi_x$$

- $\phi$  and  $\psi$  are functions of  $x$  and  $y$   $\phi(x, y), \psi(x, y)$

$$d\phi = \frac{d\phi}{dx} dx + \frac{d\phi}{dy} dy = u dx + v dy = W \cos \theta dx + W \sin \theta dy$$

$$d\psi = \frac{d\psi}{dx} dx + \frac{d\psi}{dy} dy = -\frac{p_0}{\rho} v dx + \frac{p_0}{\rho} u dy = -\frac{p_0}{\rho} W \sin \theta dx + \frac{p_0}{\rho} W \cos \theta dy$$

- Solve for  $dx$  and  $dy$

$$W \begin{bmatrix} \cos \theta & \sin \theta \\ -\frac{p_0}{\rho} \sin \theta & \frac{p_0}{\rho} \cos \theta \end{bmatrix} \begin{pmatrix} dx \\ dy \end{pmatrix} = \begin{pmatrix} d\phi \\ d\psi \end{pmatrix} \Rightarrow \begin{pmatrix} dx \\ dy \end{pmatrix} = \frac{1}{W} \begin{bmatrix} \dots \end{bmatrix}$$

← seen this transform before?

After some work

$$(M^2 - 1) \psi_{\theta\theta} = (1 + M^2) w \psi_w + w^2 \psi_{ww}$$

or

$$\tau^2 (1 - \tau) \psi_{\tau\tau} + \tau \left( 1 + \frac{2 - \gamma}{\gamma - 1} \tau \right) \psi_\tau + \frac{1}{4} \left( 1 - \frac{\tau}{\tau^*} \right) \psi_{\theta\theta} = 0$$

$$\text{where } M^2 = \left( \frac{2}{\gamma - 1} \right) \left( \frac{\tau}{1 - \tau} \right)$$

When  $M=0$

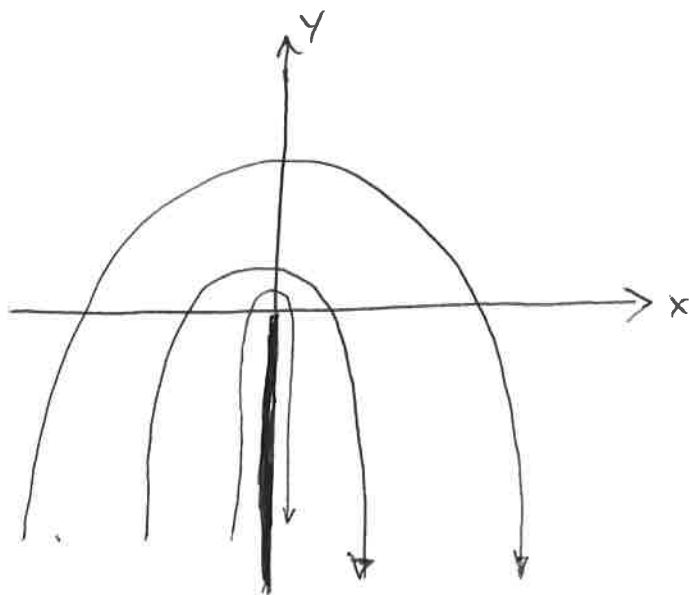
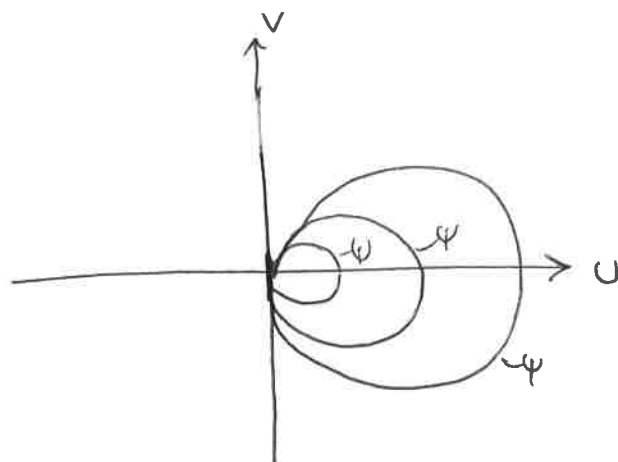
$$-\psi_{\theta\theta} = w\psi_w + w^2\psi_{ww}$$

one solution is

$$\psi = \frac{\cos\theta}{w}$$

$$U = w \cos\theta = w^2\psi$$

$$V = w \sin\theta = w(\sin^2\theta)^{1/2} = w(1 - \cos^2\theta)^{1/2} \\ = w(1 - \psi^2 w^2)^{1/2}$$



# Compressible Solution (Ringleb in 1940)

$$\psi = \frac{\cos \Theta}{r^{1/2}}$$

## Advantages:

- Compressible Euler solution to fluid dynamics!
- Simple solution form in  $\psi$
- perfect for verification + validation (V+V)
  - ↑ compare to exact soln
  - ↑ compare to experimental data
- Shows conceptual behavior of supersonic ↔ subsonic flows.

## Disadvantages:

- Solution in velocity frame. ~~not~~
- Very unlikely to fit  $x, y$  boundary conditions for real flows!
- Needs a specially prepared domain for verification of numerical solutions and BCs
- Other solutions? Good luck.

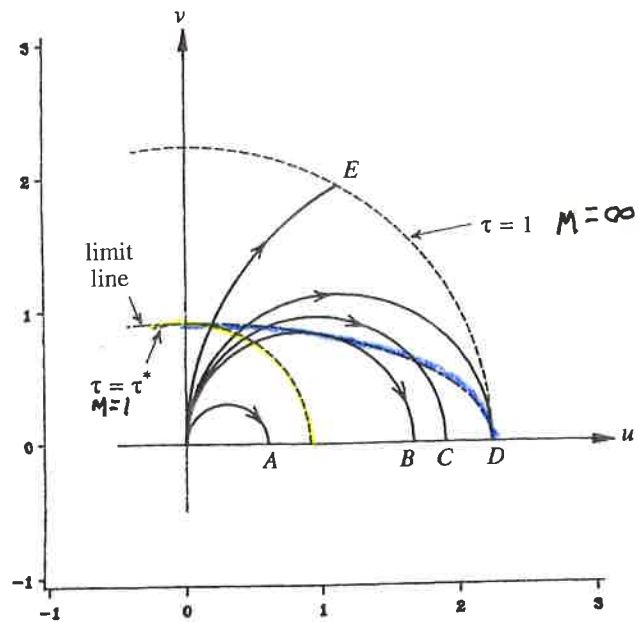


FIGURE 7.5 Compressible Ringleb solution in the hodograph plane,  $\gamma = 7/5$ .

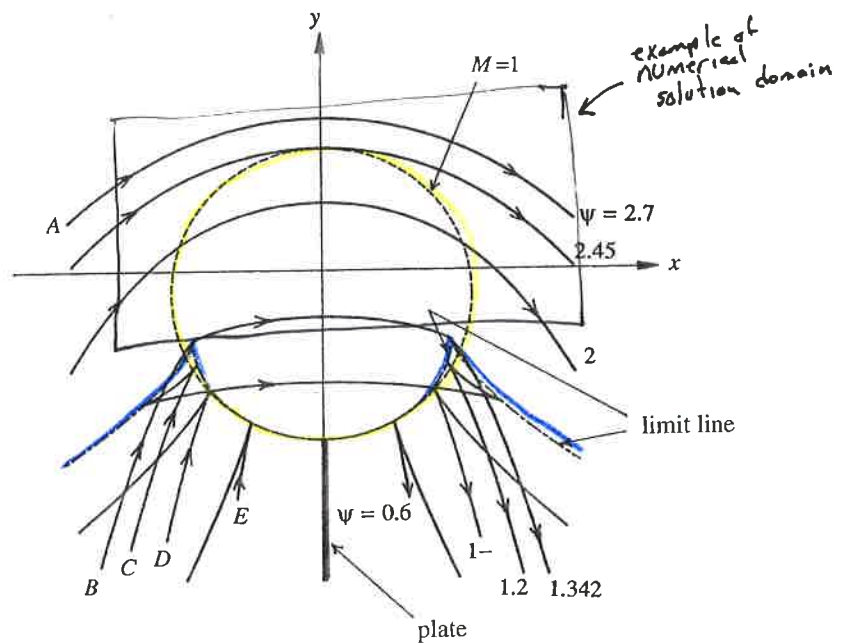


FIGURE 7.6 Streamlines, sonic line, and limit line of the compressible Ringleb solution,  $\gamma = 7/5$ .